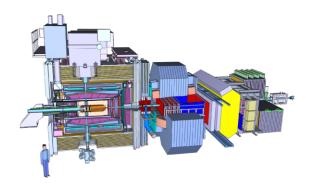


Structure of the PANDA Detector Control System

Tobias Triffterer

The PANDA Experiment



- Key experiment at FAIR, located at High Energy Storage Ring (HESR)
- Fixed target experiment, antiproton beam
- $1.5\,\mathrm{GeV}/c < p_{\overline{p}} < 15\,\mathrm{GeV}/c$



Detector Control System (DCS)

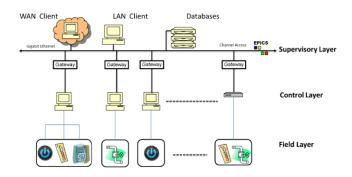
- One of the main components in the operation of a detector
- Purpose:
 - Ensure safe, correct and efficient operation
 - ► Contribute to collection of high-quality data
- Tasks:
 - Monitor the status of the detector (temperature, voltage, current, pressure etc.)
 - Control the front-ends and services of the detector (power supplies, chillers, heaters, valves, pumps etc.)
 - ► Archive all sensor data and commands for further use ⇒ see HK 52.35
 - Inform the shift crew in case any parameter exceeds its threshold or any device malfunctions



Challenges for the PANDA DCS

- PANDA consists of 30 detector subsystems
- Subsystems are built and tested by different universities/institutes around the world, but must fit together once shipped to Darmstadt
- Subsystems must be able to run autonomously for testing/maintenance and collectively for beamtime
- ⇒ The PANDA DCS must be scalable, distributed and extensible



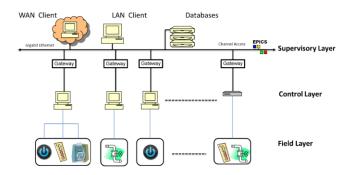


PANDA DCS split intro three layers

PANDA DCS Structure

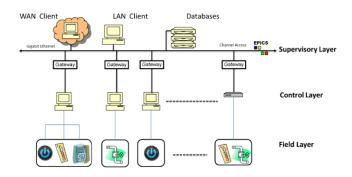
- Supervisory layer
- Control layer
- Field layer





- Field layer:
 - Front-end devices, sensors, actuators, power supplies

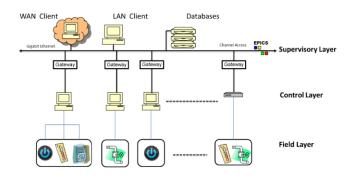




Control layer:

- Separate network for every subsystem of PANDA
- Computers to control and operate devices on the field layer
- Computers used: Normal PCs, single-board computers (e. g. Raspberry Pi), dedicated real-time hardware





- Supervisory layer:
 - Common system for all of PANDA

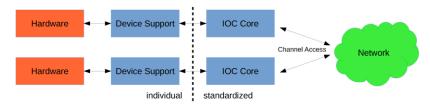
PANDA DCS Structure

- Graphical interface for shift crew
- Central databases for archiving



Central software of the DCS: EPICS

- Experimental Physics and Industrial Control System
- Toolset to create individual control system
- IOCs (Input/Output Controller) building blocks of EPICS-based DCS
 - IOCs use "Device Support" to monitor/control hardware
 - ► IOCs communicate via custom protocol (Channel Access, abbrev. CA) to other IOCs and clients on the network
- Standardized access to all devices via CA
- Number of IOCs on the network virtually unlimited





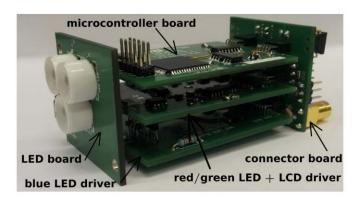
- Device Support for many devices available from the EPICS Community as open source software
- For several devices, we programmed a custom EPICS device support
- Especially for devices created within PANDA





 THMP: Temperature and Humidity Monitoring Board for PANDA





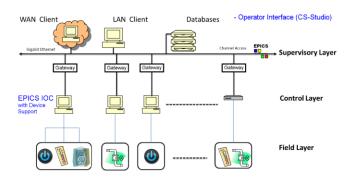
- LED Pulser for the PANDA electromagnetic calorimeter (EMC)
- ⇒ Test the readout chain of the EMC





- Device Support for High Voltage power supplies from iseg Spezialelektronik GmbH
- Written by PANDA member Florian Feldbauer
- iseg now ships their devices with built-in EPICS support based on Florian's work



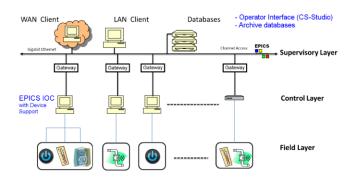


- Control System Studio (CS-Studio)
 - Graphical interface for operators

PANDA DCS Structure

Based on Eclipse RCP

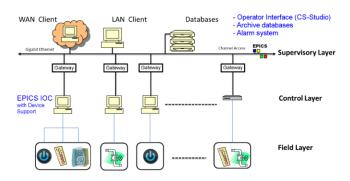




Archive system

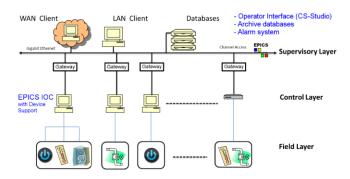
- Archive all parameters in a database
- Software to be used not yet decided
- Options: CS-Studio Archive Engine, Cassandra PV Archiver, etc.





- Alarm system
 - BEAST (part of the CS-Studio project)
 - Alert shift crew if parameter exceeds threshold
 - Inform subsystem expert automatically

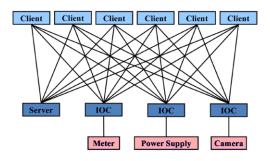




 Extensible: New software can easily be added using the EPICS CA library



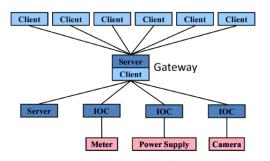
Network Structure and Encapsulation



Problem:

- Structure network into proper subdivisions (subnets)
- Protect against shift crew errors and attacks from outside

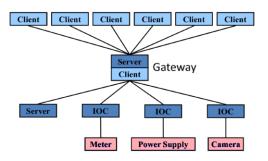
Network Structure and Encapsulation



- Separate subnet for every PANDA subsystem
- Additional subnet for the supervisory layer
- CA gateway regulates data flow accross subsystem boundaries and enforces access control
- ⇒ Provide proper encapsulation of each subsystem



Network Structure and Encapsulation



- Autonomous tests and maintenance of a subsystem
- A subsystem will not accept a potentially dangerous command from the supervisory layer (e.g. shift crew)
- Subsystem experts can access computers inside the subnet of the subsystem via VPN+SSH



Summary

- PANDA DCS based on FPICS and CS-Studio
- PANDA DCS split into layers and subnets
- Divide complex problem into a set of easier problems that can be solved separately
- Components built at 64 universities/institutes from 19 countries must work together as a distributed but coherent control system.

Thank you for your attention!



10